FLUID MECHANICS I SEMM 2313

REYNOLDS TRANSPORT THEOREM FOR MOMENTUM EQUATION

$$\frac{DN_{sys}}{Dt} = \frac{\partial}{\partial t} \int_{cv} \rho b \cdot d\forall + \int_{cs} \rho b \cdot (V \cdot \hat{n}) \cdot dA$$

If $\frac{DN_{sys}}{Dt}$ is a force; N_{sys} must be a momentum.

$$\frac{DN_{sys}}{Dt} = F = ma = \frac{D(mV)}{Dt}$$
$$N_{sys} = mV$$
$$b = V$$

Where *V* is velocity of moving fluid.

From the Reynolds Transport Theorem general equation;

$$\frac{DN_{sys}}{Dt} = F = ma = \frac{D(mV)}{Dt} = \frac{\partial}{\partial t} \int_{cv} \rho b \cdot d\forall = \frac{\partial}{\partial t} \int_{cv} \rho(V) \cdot d\forall$$

$$F = \frac{D(mV)}{Dt} = \frac{\partial}{\partial t} \int_{cv} \rho(V) \cdot d\forall + \int_{cs} \rho(V) \cdot (V \cdot \hat{n}) \cdot dA$$

Where *V* is velocity and \forall is volume.

In general, Reynolds Transport Theorem for momentum equation can be written as:

$$\sum F = \frac{\partial}{\partial t} \int_{cv} \rho(V) \cdot d\forall + \int_{cs} \rho(V) \cdot (V \cdot \hat{n}) \cdot dA$$

 $(V) \neq (V \cdot \hat{n})$

V = Velocity of moving fluid

 $V \cdot \hat{n} =$ Velocity of fluid compare with vector \hat{n}

For incompressible and steady flow, velocity of fluid did not change with time, it is means that;

$$\frac{\partial}{\partial t} \int_{cv} \rho(V) \cdot d \forall = 0$$

Momentum equation can be simplified as:

$$\sum F = \int_{cs} \rho(V) \cdot (V \cdot \hat{n}) \cdot dA$$

In some textbook, it is written as:

$$\sum F = \sum \rho AV \cdot (V \cdot \hat{n}) \sum \rho Q \cdot (V \cdot \hat{n})$$

Please remember this:

 $(V) \neq (V \cdot \hat{n})$

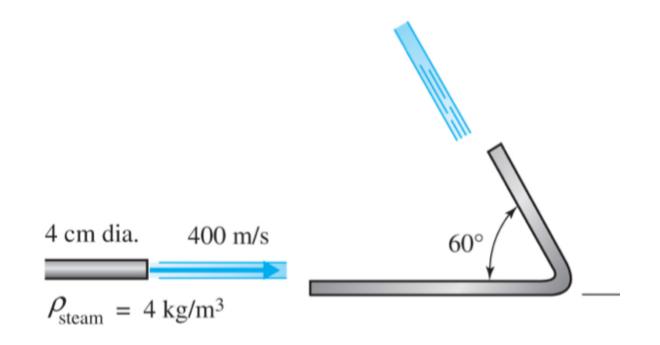
V = Velocity of moving fluid

A =Cross-sectional area of moving fluid

 $V \cdot \hat{n} =$ Velocity of fluid compare with vector \hat{n}

Determine the force component of superheated steam acting on the blade.

- a) The blade is stationary
- b) The blade moves to the right at 100 m/s
- c) The blade moves to the left at 100 m/s



Sketch the control volume and its important information.

P.A. coso Va Sin O P.A. 10 P2A2 sin O Q 203 . EV P2A2 12 Ð n Æ >V1

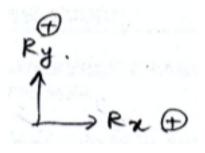
Here,

$$\sum F$$
 = Total force that occur due to pressure and reaction force

So that, in the control volume diagram, we need to add force due to the pressure and the reaction force that occur in the system.

Force due to the pressure must act perpendicular to the control surface.

Reaction force (normally) predicted as this. Our final calculation could determine whether its direction correct or not.



$$\sum F = \sum p.Vh.A.V$$

$$R_{x} + P_{i}A_{i} + P_{s}A_{s}\cos\theta = p(-V_{i})A_{i}(V_{i}) + p(V_{s})A_{s}(-V_{s}\cos\theta)$$

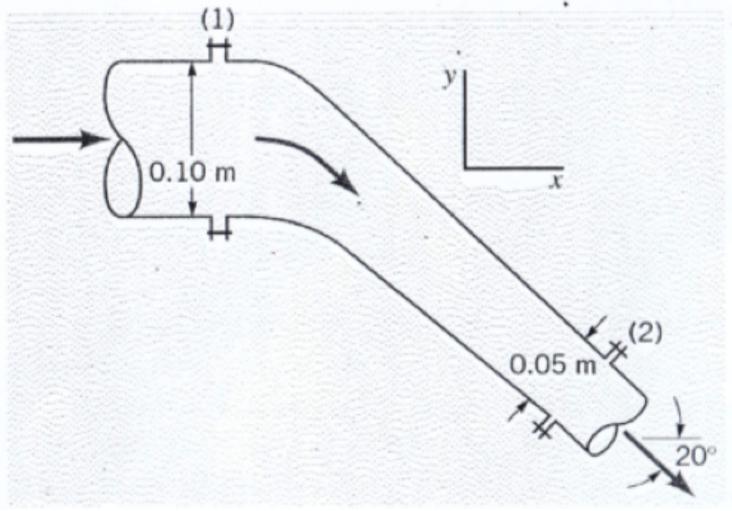
$$R_{x} = (4)(-400)(\overline{u})(0.04)^{2}(400) + (4)(400)(\overline{u})(0.04)^{2}$$

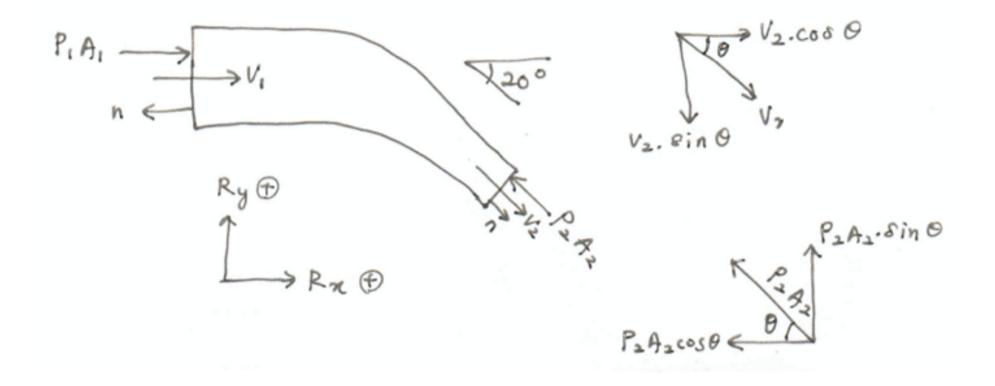
$$(-400\cos\theta)$$

$$= -804.352 - 402.176$$

$$Ry(\downarrow) = 696(N)$$

Water flows through the 20° reducing bend at rate 0.025 m³/s. The flow is frictionless, gravitational effects are negligible and the pressure at section (1) is 150 kPa. Determine the x and y components of force required to hold the bend in place.





 $R_{x} + P_{A_{1}} - P_{2}A_{2}\cos\Theta = P_{A_{1}}(-V_{1})(V_{1}) + P_{A_{2}}(V_{2})(V_{2}\cos\Theta)$

component P., P2, V, V2 perlu dicari

Pressure bolch dikira deugan menggunakan Bernoulli equation.

velocity bolch diselesaikan dengan menggunakan continuity equation.

$$Q = A_{1}V_{1} = A_{2}V_{2}$$

$$0.025 = A_{1}V_{1} = \frac{w}{4}(0.1)^{2}.V_{1}$$

$$V_{1} = 3.18 \text{ m/s}.$$

$$V_{2} = (2.73 \text{ m/s}.$$

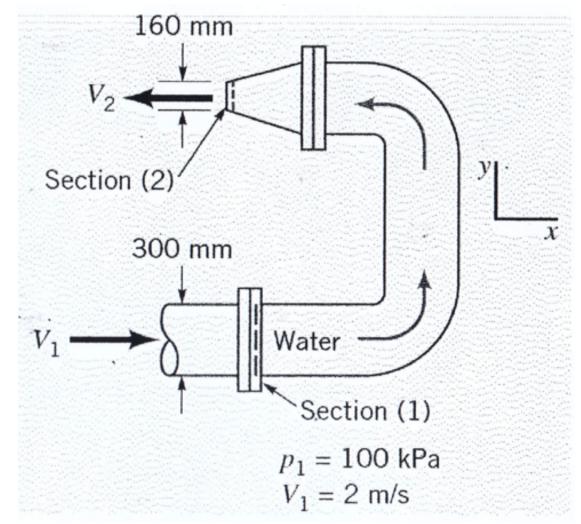
$$\frac{P_{1}}{P_{q}} + \frac{V_{1}^{2}}{2g} = \frac{P_{2}}{P_{g}} + \frac{V_{1}^{2}}{2g}$$

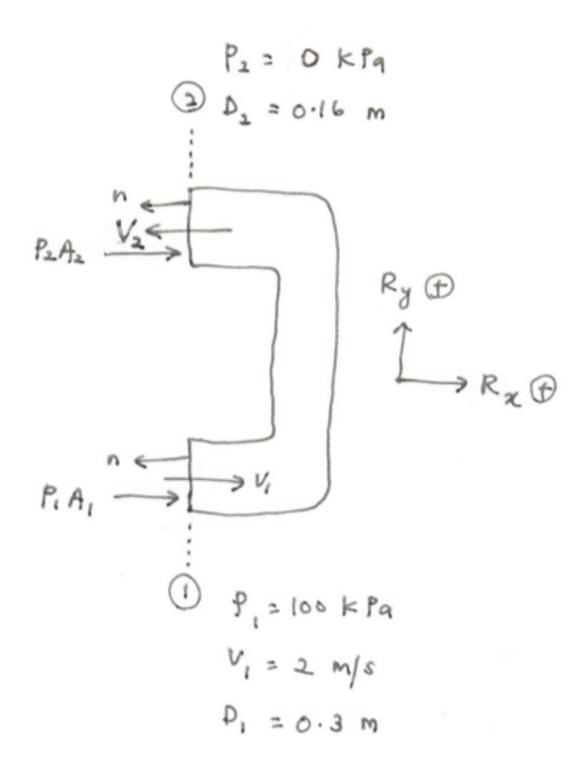
$$P_{1} = 150 \text{ kPa.}$$

$$P_{2} = 74 \text{ kPa.}$$

nasukkan nilai yang diperdeli dalam persamaan linear momentum. Rx = - 822(N) Tanda negatif menunjukkan Rx bertindak pada arah yong berlawanan. Ry = -157.7 (N)

Determine the magnitude and direction of the anchoring force needed to hold the horizontal elbow and nozzle combination shown below in place. The gage pressure at section (1) is 100 kPa. At section (2), the water exits to the atmosphere.





$$F_{\pi} = \sum p A V_{h} \cdot V_{\pi}.$$

$$R_{\pi} + P_{i} A_{i} + P_{2} A_{2} = p A_{i} (-V_{i}) (V_{i}) + p A_{2} (V_{2}) (V_{2})$$

$$P_{cdm} = 0$$

$$From \quad A_{1} V_{i} = A_{2} V_{2}$$

$$V_{2} = 7.03 \text{ m/s}$$

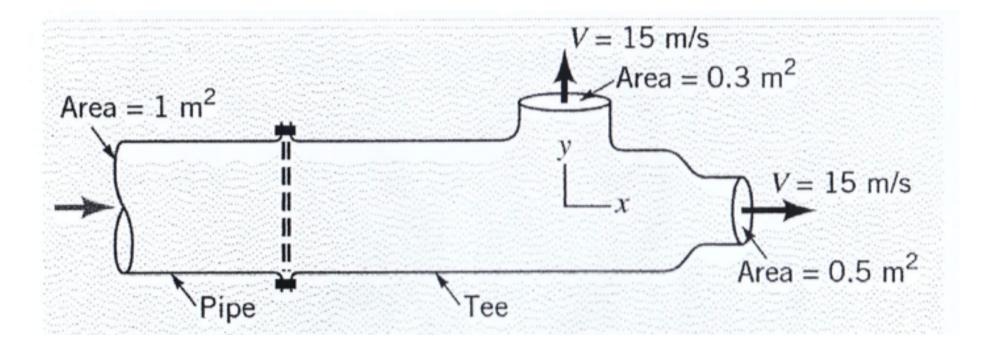
$$R_{\pi} = 1000 \left(\frac{E}{4}\right) (0.3)^{2} (-2) (2) + 1000 \left(\frac{E}{4}\right) (0.16)^{2} (7.03 \times 7.03)$$

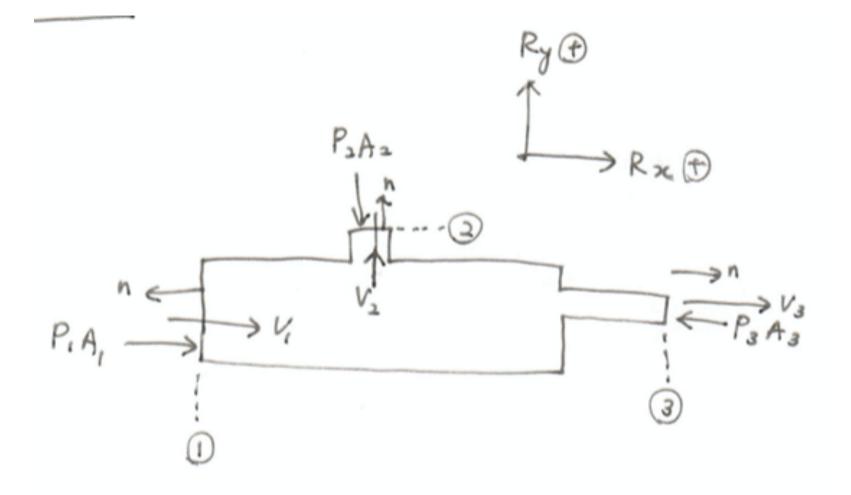
$$- 100 \times 10^{3} \left(\frac{E}{4}\right) (0.3)^{2}$$

$$R_{\pi} = -6358.5 (N)$$

$$R_{g} = 2ero (tial_{n})$$

Water flows as two free jets from the tee attached to the pipe. The exit speed is 15 m/s. If viscous effects and gravity are negligible, determine the x and y components of force that the pipe exerts on the tee





$$P_{2} = P_{3} = P_{atm} = 0$$

$$Q_{in} = Q_{out}$$

$$Q_{i} = Q_{2} + Q_{3}$$

$$A_{i}V_{i} = A_{2}V_{2} + A_{3}V_{3}$$

$$\therefore V_{i} = I_{2} m/s.$$

Energy I = Energy (2)

$$\frac{P_i}{P_i} + \frac{V_i^2}{2g} = \frac{P_2}{P_g} + \frac{V_i^2}{2g}$$

$$\frac{P_2}{P_g} + \frac{V_i^2}{2g}$$

$$\frac{x - \text{direction} :}{F_x = \sum p A V_n \cdot V_x}.$$

$$R_x + P_i A_i - P_3 A_3 = p A_i (-V_i)(V_i) + p A_2 (V_2)(o) + p A_3 (V_3)(V_3)$$

$$\uparrow$$

$$R_x = -72 \text{ kN}.$$

$$R_x = -72 \text{ kN}.$$

$$Trada \text{ velocity}$$

$$arah - x \text{ pada}$$

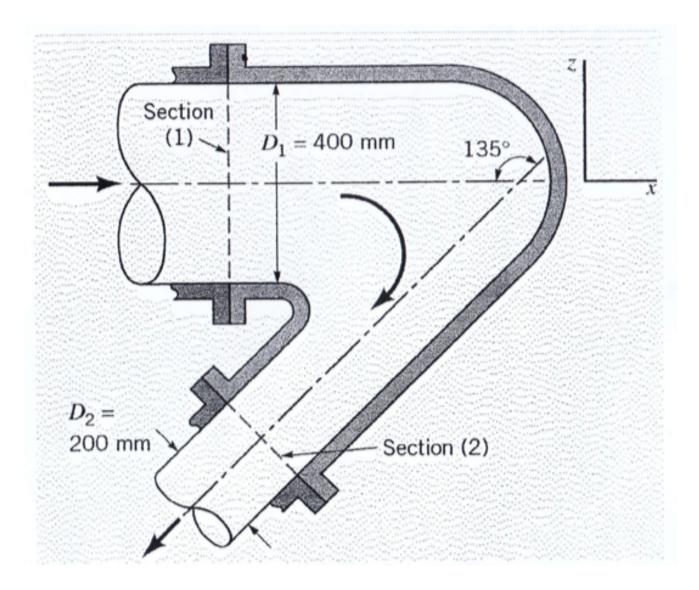
$$point 2.$$

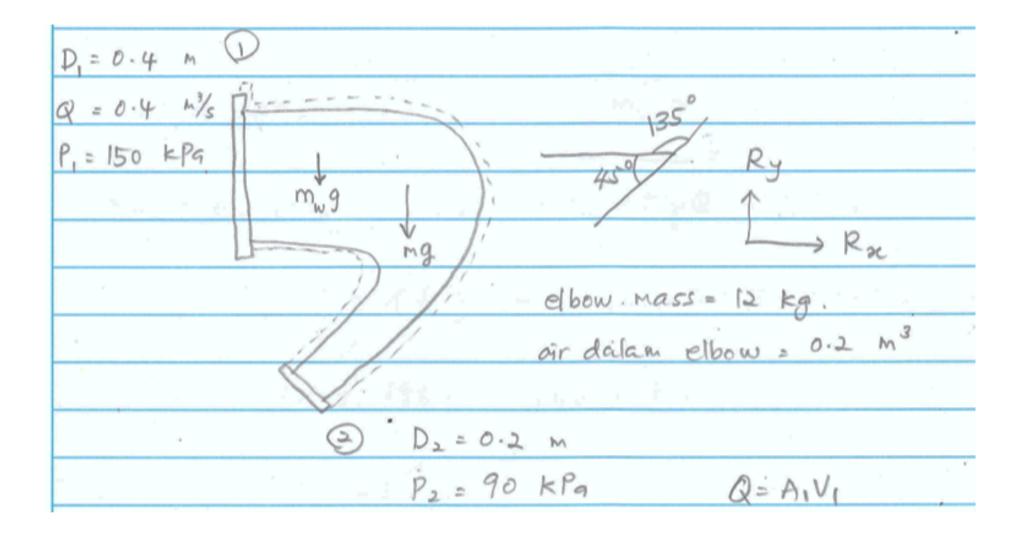
$$R_{y} + (-P_{2}A_{2}) = PA_{2}(V_{2})(V_{1})$$

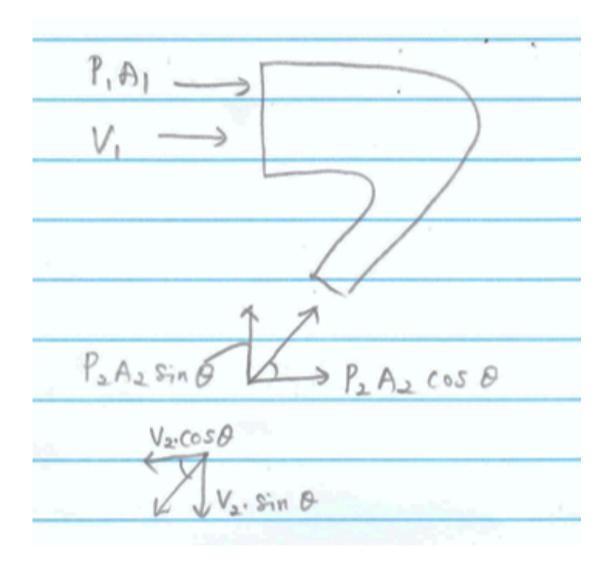
$$\uparrow$$

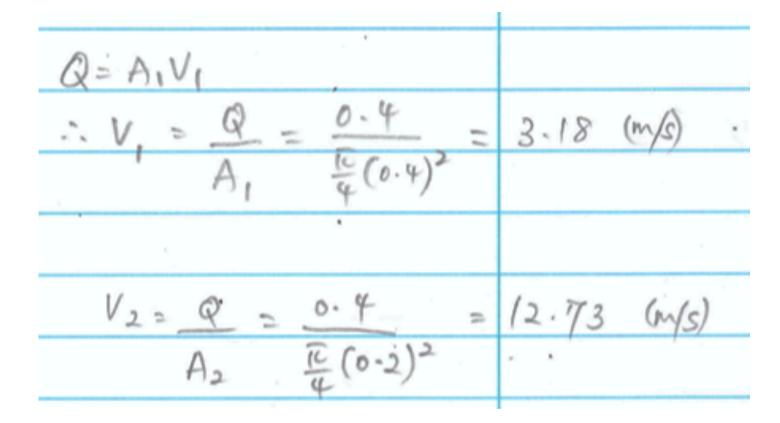
$$P_{atm} = 0$$

A converging elbow turns water through an angle of 135° in a vertical plane. The flow cros section diameter is 400 mm at the elbow inlet (section 1), and 200 mm at the elbow outlet (section 2). The elbow flow passage volume is 0.2 m³ between section 1 and 2. The water volume flow rate is 0.4 m3/s and the elbow inlet and outlet pressures are 150 kPa and 90 kPa. The elbow mass is 12 kg. Calculate the horizontal (x-direction) and vertical (z-direction) anchoring forces required to hold the elbow in place.









Rx + P, A, + P2A2 cos 0 = V, p(-V,A,) +	$(-V_{2}\cos\theta)p(A_{2}V_{2})$	
		1
Rx+P,A, + P,A2000 0 = -V, PQ -	- V2 cos & pQ	
Rol = - VIPQ - V2 cos Q. PQ - PIA, - P2A	2 COS 8	
= - (3.18)(1000)(0.4) - (12.73)(0.707)(10	$(00)(0.4) - (150 \times 10^3)(\frac{10}{4})(10)$	·(+) ²) -
	(gox 103)(#(0.2)2)
= -1272 - 3600 - 18849.6 - 20	827.4	1 and 1 and
= -26.55 KN		
negative menunjukkan arah	berlawanan	
R _×		·

Ry + P2A2 Sing - Mpipe g - Mw.g = - V2 Sind . pA2V2	x
Ry = Mpipe g + Mwater g - V2 Sind pQ - P2A2Sin O	
= 12(9.81) + pV.g - (12.73)(0.707)(1000)(0.4) - (90×103)	$\left(\frac{\overline{u}}{\psi}(0\cdot 2)^{*}\right)(0\cdot 707)$
= 117.72 + 1962 - 3600 - 1999	
= -3519.28	
	· • •
Ry.	